# STAT 542: Statistical Learning

Boosting

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- AdaBoost
- Training error bound
- · Gradient boosting



# Boosting

Consider producing a sequence of learners:

$$F_T(x) = \sum_{t=1}^T f_t(x)$$

How to train each f<sub>t</sub>(x)? At the *t*-th iteration, given perviously estimated f<sub>1</sub>,..., f<sub>t-1</sub>, we estimate a new function h(x) to minimize the loss:

$$\min_{h} \sum_{i=1}^{n} L\left(y_i, \sum_{k=1}^{t-1} f_k(x_i) + h(x_i)\right)$$

• Instead of using the entire h(x), we only use a small "fraction" of it, and add  $\alpha_t h(x)$  to the current model. Then proceed to the next iteration.

- Boosting is an additive model, but its different from **generalized** additive model, in which each weak learner only involves one variable, and we fit p of such functions. In boosting, each  $f_t(x)$ can be very flexible, and we may fit a large number of functions.
- Boosting is also different from random forests, another additive model. In random forests, each tree is generated independently, so they can't borrow information from each other.
- AdaBoost (Freund and Schapire, 1997) is a special case of this framework with Exponential loss for classification.
- For this setting, we use labels  $y_i \in \{-1, 1\}$ .

### AdaBoost: algorithm

- 1. Initiate subject weights  $w_i^{(1)} = 1/n$ , i = 1, 2, ..., n.
- 2. For t = 1 to T, repeat (a) (d)
  - (a) Fit a classifier  $f_t(x) \in \{-1, 1\}$  to the training data, with individual weights  $w_i^{(t)}$ .
  - (b) Compute the training error at t

$$\epsilon_t = \sum_i w_i^{(t)} \mathbf{1}\{y_i \neq f_t(x_i)\}$$

(c) Compute

$$\alpha_t = \frac{1}{2} \log \frac{1 - \epsilon_t}{\epsilon_t}$$

•••

- 2. continued
  - (d) Update weights

$$w_i^{(t+1)} = \frac{w_i^{(t)}}{Z_t} \exp[-\alpha_t y_i f_t(x_i)],$$

where  $Z_t$  is a normalization factor to keep  $w_i^{(t+1)}$  a distribution:

$$Z_t = \sum_{i=1}^n w_i^{(t)} \exp[-\alpha_t y_i f_t(x_i)],$$

3. Output the final model

$$F_T(x) = \sum_{t=1}^T \alpha_t f_t(x)$$

And the classification rule:  $sign(F_T(x))$ 

- · Let's look at an example with the following data
- At each iteration, we build a tree model  $f_t(x)$  with just one split
- · The final model is stacked with all tree models



- At the first iteration, the tree splits at 0.25 for X<sub>1</sub>
- This makes the three positive cases on the right hand side to increase their weights



- At the second iteration, the tree splits at 0.65 for X<sub>2</sub>
- This further adjusts the weights, along with calculating  $\alpha_t$  at each step.



- At the second iteration, the tree splits at 0.85 for X<sub>1</sub>
- This produces the final model:

$$F_3(x) = 0.4236 \cdot f_1(x) + 0.6496 \cdot f_2(x) + 0.9229 \cdot f_3(x)$$



- · At the initial step, we treat all subject with equal weight
- Learn a classifier  $f_t(x)$  and inspect which subjects got mis-classified.
- Put more weights on the mis-classified subjects for the next iteration
- Add  $\alpha_t f_t(x)$  to the existing model and train the next iteration using the updated weights

- Why  $\alpha_t$  is choosing this way  $\alpha_t = \frac{1}{2} \log \frac{1-\epsilon_t}{\epsilon_t}$ ?
- Why the weak classifier is chosen to minimize the weighted error?
- What can we say about the performance of the final model  $F_T(x)$

# **Training Error Bound**

· Let's start with analyzing the weight after the final iteration:

$$w_i^{(T+1)} = \frac{1}{Z_T} w_i^{(T)} \exp[-\alpha_t y_i f_T(x_i)]$$

• Note that for  $w_i^{(T)}$ , we can also further back-track it into T-1.

$$w_i^{(T)} = \frac{1}{Z_{T-1}} w_i^{(T-1)} \exp[-\alpha_t y_i f_{T-1}(x_i)]$$

· Hence, we can track this all the way back to the first iteration

# The Subject Weights

• This gives

$$w_i^{(T+1)} = \frac{1}{Z_1 \cdots Z_T} w_i^{(1)} \prod_{t=1}^T \exp[-\alpha_t y_i f_t(x_i)]$$
$$= \frac{1}{Z_1 \cdots Z_T} \frac{1}{n} \prod_{t=1}^T \exp[-\alpha_t y_i f_t(x_i)]$$
$$= \frac{1}{Z_1 \cdots Z_T} \frac{1}{n} \exp\left[-y_i \sum_{t=1}^T \alpha_t f_t(x_i)\right]$$

• Note that  $\sum_{t=1}^{T} \alpha_t f_t(x_i)$  is the just the final model at the *T*-th iteration, i.e.,  $F_T(x_i)$ .

# **The Subject Weights**

· Noticing that the weights sum up to 1, we have

$$1 = \sum_{i=1}^{n} w_i^{(T+1)} = \frac{1}{Z_1 \cdots Z_T} \frac{1}{n} \sum_{i=1}^{n} \exp\left\{-y_i F_T(x_i)\right\}$$

or

$$Z_1 \cdots Z_T = \frac{1}{n} \sum_{i=1}^n \exp\left\{-y_i F_T(x_i)\right\}$$

• On the right-hand side, it is the exponential loss.

## **The Exponential Loss**

- Let's check some facts:
  - Correctly classified: sign(y) = sign(f(x)), and exp[-yf(x)] > 0
  - Incorrectly classified: sign(y) = -sign(f(x)) the exp[-yf(x)] > 1
- Hence, the exponential loss is larger than 0/1 loss:

$$Z_1 \cdots Z_T$$

$$= \frac{1}{n} \sum_{i=1}^n \exp\left\{-y_i F_T(x_i)\right\}$$

$$> \frac{1}{n} \sum_{i=1}^n \mathbf{1}\left\{y_i \neq F_T(x_i)\right\}$$

- On the other hand, we can further break down each  $Z_t$
- Notice that  $f_t(x_i)$  is a classification model with output 1 or -1, this either matches or not matches  $y_i$ :

$$Z_{t} = \sum_{i=1}^{n} w_{i}^{(t)} \exp[-\alpha_{t} y_{i} f_{t}(x_{i})]$$
  
= 
$$\sum_{y_{i}=f_{t}(x_{i})} w_{i}^{(t)} \exp[-\alpha_{t}] + \sum_{y_{i}\neq f_{t}(x_{i})} w_{i}^{(t)} \exp[\alpha_{t}]$$
  
= 
$$\exp[-\alpha_{t}] \sum_{y_{i}=f_{t}(x_{i})} w_{i}^{(t)} + \exp[\alpha_{t}] \sum_{y_{i}\neq f_{t}(x_{i})} w_{i}^{(t)}$$

• By our definition,

$$\epsilon_t = \sum_i w_i^{(t)} \mathbf{1} \big\{ y_i \neq f_t(x_i) \big\}$$

is the proportion of weights for mis-classified samples.

· Hence,

$$Z_t = (1 - \epsilon_t) \exp[-\alpha_t] + \epsilon_t \exp[\alpha_t]$$

• Since we want to minimize  $Z_1 \cdots Z_t$ , we can simply minimize  $Z_t$  by choosing  $\alpha_t$ 

## The $Z_t$ 's

• Take a derivative with respect to  $\alpha_t$ , we have

$$-(1 - \epsilon_t) \exp[-\alpha_t] + \epsilon_t \exp[\alpha_t] = 0$$

· This gives

$$\alpha_t = \frac{1}{2}\log\frac{1-\epsilon_t}{\epsilon_t}$$

And plug this back into Z<sub>t</sub>

$$Z_t = 2\sqrt{\epsilon_t(1-\epsilon_t)}$$

 Since ε<sub>t</sub>(1 − ε<sub>t</sub>) can only attain maximum of 1/4, Z<sub>t</sub> must be smaller than 1. And Z<sub>1</sub> ··· Z<sub>t</sub> should converge to 0.

# **The Training Error**

- Alternatively, if we let  $\gamma_t = \frac{1}{2} - \epsilon_t$  as the improvement from a random model

$$Z_t = 2\sqrt{\epsilon_t(1-\epsilon_t)}$$
$$= \sqrt{1-4\gamma_t^2}$$
$$\leq \exp\left[-2\gamma_t^2\right]$$

· The last equation uses the Taylor expansion that

$$\exp\left[-4\gamma_t^2\right] = 1 - 4\gamma_t^2 + \cdots$$

· Hence, the AdaBoost training error is bounded above by

Training Error 
$$= \sum_{i=1}^{n} \mathbf{1} \{ y_i \neq \operatorname{sign}(F_T(x_i)) \}$$
$$= \sum_{i=1}^{n} \exp\left[ -y_i \neq F_T(x_i) \right]$$
$$= Z_1 \cdots Z_T$$
$$\leq \exp\left[ -2\sum_{t=1}^{T} \gamma_t^2 \right]$$
$$\to 0$$

as long as  $f_t(x)$  at each iteration t is better than random guess.

- The Adaboost outputs a classifier  $F_T(x)$  with small testing error? No. We need to tune *T*. Careful! — You can easily overfit.
- The training error of  $F_T(x)$  decreases w.r.t. *T*? No. Its only the upper bound of 0/1 training error
  - After each iteration, Adaboost decreases a particular upper-bound of the 0/1 training error. So in a long run, the training error is going to zero, but not necessarily monotonically.
- We can use a classifier that is worse than random guessing? Yes. The reverse of that classier can be used ( $\alpha_t < 0$ )
- In practice, a classification tree model is used as the weak learner.

### Remarks

- · We may also roughly calculate the estimated probability
- Consider the (upper bound) exponential loss  $\mathsf{E}(\exp\{-yF(x)\})$ , which is

$$e^{-F(x)}P(Y=1|x) + e^{F(x)}P(Y=-1|x)$$

• The best F(x) that minimize this expectation should be

$$-e^{-F(x)}P(Y=1|x) + e^{F(x)}P(Y=-1|x) = 0$$

· This leads to

$$F(x) = \frac{1}{2} \log \frac{\mathsf{P}(y=1|x)}{\mathsf{P}(y=-1|x)}$$
$$\mathsf{P}(y=1|x) = \frac{e^{2F(x)}}{1+e^{2F(x)}}$$

## AdaBoost



**Boosting Iterations** 

## **R** implementation

- Use R package gbm: function gbm
- · Tuning parameters:
  - Specify distribution = "adaboost"
  - n.trees controls the number of iterations T
  - shrinkage : further set a shrinkage factor on each  $f_t(x)$ . The default is 0.01. The original AdaBoost uses 1, however, can be less stable. A small value of this will require a large number of trees.
  - bag.fraction : each  $f_t(x)$  uses a bootstrapped sample. If set to < 1, two different runs will produce slightly different models
  - cv.folds : number of cross validations
- Other parameters to consider: interaction.depth = 1 means stumps (additive model), > 1 allows interations

# An Example



# **Gradient Boosting**

· In more general framework, consider additive structure:

$$F_T(x) = \sum_{t=1}^T \alpha_t f(x; \boldsymbol{\theta}_t)$$

Fit model by minimizing the loss function

$$\min_{\{\alpha_t, \boldsymbol{\theta}_t\}_{t=1}^T} \sum_{i=1}^n L(y_i, F_T(x_i))$$

- · We may choose
  - Loss function *L*, suitable for the problem
  - Base learner  $f(x; \theta)$  with parameter  $\theta$ , such as linear, tree, etc.

### Forward Stage-wise Additive Model

- It is difficult to minimize over all  $\{\alpha_t, \theta_t\}_{t=1}^T$ .
- Instead, we do this in a stage-wise fashion. (recall the connection between Lasso and stage-wise regression)
- The algorithm:
  - (1) Set  $F_0(x) = 0$
  - (2) For t = 1, ..., T
    - Choose  $(\alpha_t, \theta_t)$  to minimize the loss

$$\min_{\alpha, \theta} \sum_{i=1}^{n} L(y_i, F_{t-1}(x_i) + \alpha f(x_i; \theta))$$

• Update  $F_t(x) = F_{t-1}(x) + \alpha_t f(x; \theta_t)$ 

- AdaBoost is forward stage-wise using exponential loss.
- It doesn't pick an optimal  $f(x; \theta)$  at each step: the tree model is not optimized, we just need some model that is better than random.
- Only the step size  $\alpha_t$  is optimized at each t given the fitted  $f(x;\pmb{\theta}_t)$

### Forward Stage-wise Additive Model

- Another example is the forward stage-wise linear regression
- For each step we use a single variable linear model:

$$f(x,j) = \operatorname{sign}(\operatorname{Cor}(X_j,\mathbf{r}))X_j$$

- **r** is the residual, as  $r_i = y_i F_{t-1}(x_i)$
- j is the index that has the largest absolute correlation with  ${f r}$
- Then we give a very small step size  $\alpha_t$ , say,  $\alpha_t = 10^{-5}$ , and with sign equal to the correlation between  $X_j$
- *F*<sub>t</sub>(*x*) is almost equivalent to the Lasso solution path (as *t* changes)

•  $r_i$  is in fact the gradient to the squared-error loss:

$$r_{it} = -\left[\frac{\partial \left(y_i - F(x_i)\right)^2}{\partial F(x_i)}\right]_{F(x_i) = F_{t-1}(x_i)}$$

- We then fit the weak leaner  $f_t(x)$  to the residuals
- Update the fitted model  $F_t$

#### An Alternative View

- This can be generalized into any loss function L
- At each iteration *t*, calculate "pseudo-residuals", i.e., the negative gradient for each observation

$$g_{it} = -\left[\frac{\partial L(y_i, F(x_i))}{\partial F(x_i)}\right]_{F(x_i) = F_{t-1}(x_i)}$$

- Fit  $f_t(x, \theta_t)$  to pseudo-residual  $g_{it}$ 's
- Search for a step length

$$\boldsymbol{\alpha_t} = \arg\min_{\boldsymbol{\alpha}} \sum_{i=1}^n L(y_i, F_{t-1}(x_i) + \boldsymbol{\alpha} f(x_i; \boldsymbol{\theta}_t))$$

• Update  $F_t(x) = F_{t-1}(x) + \alpha_t f(x; \theta_t)$ 

# **Gradient Boosting**

• Hence, the only change when modeling different outcomes is to choose the loss function, and derive the pseudo-residuals

Setting	Loss	Negative Gradient
Regression	$\frac{1}{2}(y - f(x))^2$	$y_i - f(x_i)$
Regression	y - f(x)	$\operatorname{sign}(y_i - f(x_i))$
Classification	Deviance	$y_i - p(x_i)$

• For gradient boosting using CART as base classifier, we can make it more sophisticated by optimizing  $\alpha_t$  at each terminal node

- · Boosting is prone to over-fitting
- Fit a large number of iterations n.trees, then select *T* using CV or test set.
- It is better to take small steps: shrinkage = 0.01 as default
- Use gbm package by specifying the distribution:
  - "gaussian", "bernoulli", "laplace", "huberized", "multinomial", etc.